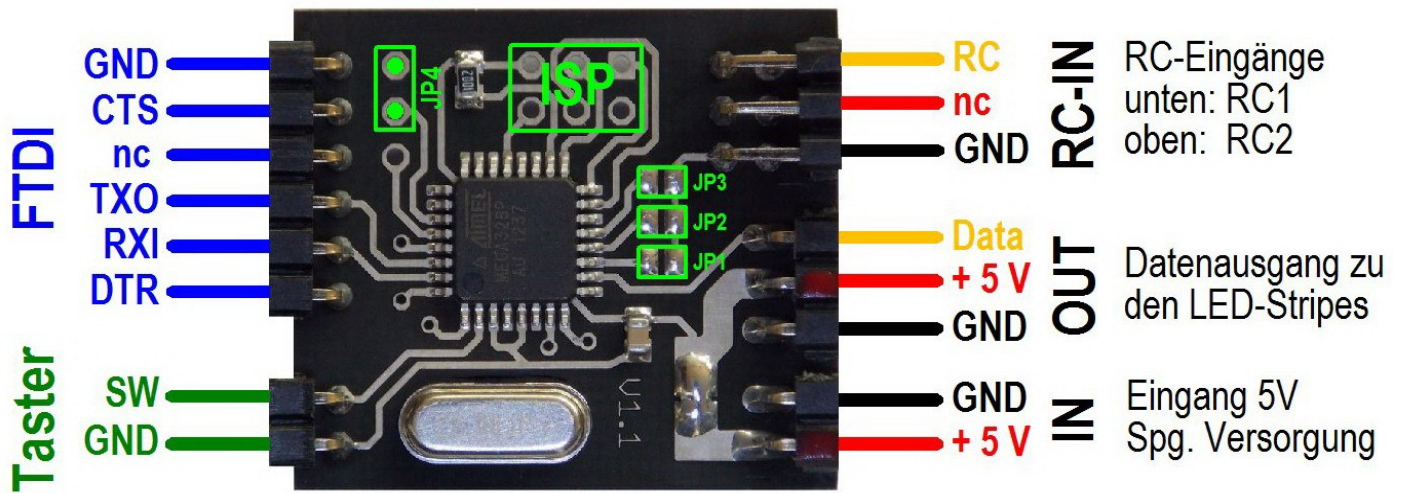


Quick Guide

1. Connectors

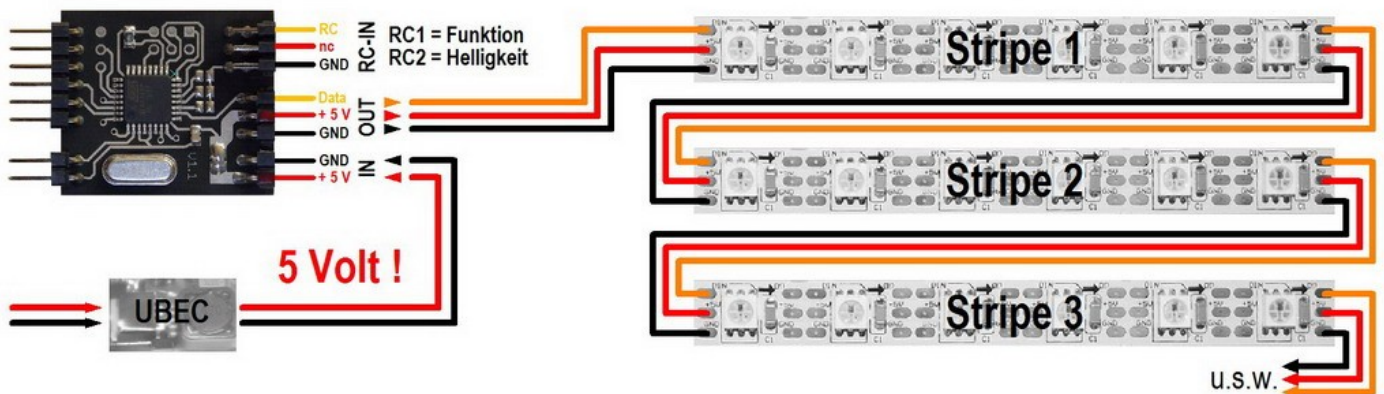


- IN:** 3.8 ... 5.0 Volt ! (avoid voltage above 5.0 V !)
- OUT:** Output for WS2812 LED-stripes (6 or 9 LEDs / outrigger)
- RC1:** RC-Ch. / AUX1 -> Selects pattern by transmitter
- RC2:** RC-Ch. /AUX.2 -> Selects brightness by transmitter
- ISP:** for bootloader install only – not needed
- FTDI:** serial FTDI connector for software update

- Taster:** connect tact-switch to select brightness (when using only 1 Rx-Ch.)
- JP1:** „Solder-Jumper“ 1 : 6-Outrigger / Hexacopter
- JP2:** „Solder-Jumper“ 2 : 8-Outrigger / Oktocopter
- JP3:** „Solder-Jumper“ 3 : operate with 1 Rx Ch.
- JP4:** Jumper 4 : open = 6 LEDs / closed 9 LEDs per outrigger

MWCLightRGB

WS2812 LED-Stripes in 6er bzw. 9er Gruppen an den Auslegern



2. Installation

Normal wiring is leading signal thru each stripe (daisy chained). Voltage supply can be connected to each segment separate, no need to lead-thru. See end of this guide for alternate wirings . Important : care for proper mount of stripes, accurate soldering and avoid from short-circuits ! **Voltage mustn't override 5.0 V DC any time ! Otherwise damage will happen to controller or/and stripes !** You can either connect segments in parallel, Data-wire has to be split to each „D-In“ of both segment – leave „D-Out“ of second segment opened ! Only master wire is to be chained to next segment ! Assure proper wiring by control with digital multimeter after wiring is completed before power-up unit .

3. Settings

Mode (Solder-Jumper JP1 + JP2):

- no jumper > Quadcopter Mode (4-Arms / Outriggers)
- JP 1 closed > Hexacopter Mode (6- Arms / Outriggers)
- JP 2 closed > Oktocopter Mode (8- Arms / Outriggers)

Number of RC-AUX Channels used (Solder-Jumper JP 3):

- JP 3 closed > One-Channel-Mode (only pattern selected by transmitter, brightness by tact-switch)
- JP 3 open > Two-Channel-Mode (Select pattern and brightness thru transmitter)

If JP3 is closed, a tact-switch is needed at the „Taster“-connector to select brightness. Brightness can be chosen in 4 steps (25 / 50 / 75 / 100 %) . Brightness will be pre-setted to 50% on startup.

Number of LED per Arm/Outrigger (Jumper JP 4):

- JP 4 closed > 9 LED´s on each segment will be controlled
- JP 4 open > 6 LED´s on each segment will be controlled

4. Entering Setup-Mode :

- Connect a tact-switch to the „Taster“-connector
- Press and hold tact-switch during boot-up, then release
- When first segment / outrigger lights up, base color can be set by RX-Channel 1(RC1) (Brightness can´t be selected)
- Switch to next segment ny pressing tact-switch short term
- Repeat setting up base color, switch to next segment
- After setting up last segemnts base color, press and hold tact-switch as long as all LEDs will light up in selected pattern. Setting are saved now .

5. Power supply

This module and WS2812 RGB-stripes are designed to work from 3.80 V DC up to 5.0 V DC. Avoid from higher voltages, even 5.1 V can cause serious damage to controller and LEDs !

Calculating power-consumption :

One segment of 6 LED´s draws 360mA of current (r.a. 1.8 W)

One segment of 9 LED´s draws 540mA of current (r.a. 2.7 W)

Example: a Hexacopter w/ 9 LED´s on each segment draws $6 \times 0,54 \text{ A} = 3,24 \text{ A}$ overall current at 100% Brightness, white light active

It´s important to assure that your BEC can provide the needed overall current to avoid damage to BEC

6. Updating Software :

For software update, only power-supply and FTDI-connector have to be connected to MWC-RGB controller – all LED-segments need to be disconnected !

Bootloader-Tool can be downloaded here :

http://www.mcselec.com/index.php?option=com_docman&task=doc_download&gid=153&Itemid=54

(this tool doesnt support Auto-reset-function, this needs to be done thru handling manually – see below)

Proceeding :

1. Install Bootloader Tool
2. select COM-Port of FTDI adaptor
3. set baudrate to 19200
4. connect FTDI cable (care for polarity !)
5. Select File
6. Start „upload“
7. Power-up your power supply. Reset of controller will follow and upload starts.
8. Progress will be shown during upload process
9. After completion, error-code „0“ should be reported (success)
10. Disconnect FTDI first, then power-down your supply

7. Technical Data :

MWCLightRGB is a microcontroller based LIM-controller (LIM : Lights in motion) for useage with digital RGB-stripes w/ built-in WS2811 controller only. No other LED-stripes are supported. Operating voltage | 3.80 5.0 V DC only .

RC-Input: Standart RC Channels, pulse-lenght 900 to 2100 μ s

LED-Bus: Data-bus for WS2811 based RGB-LEDs, daisy-chained

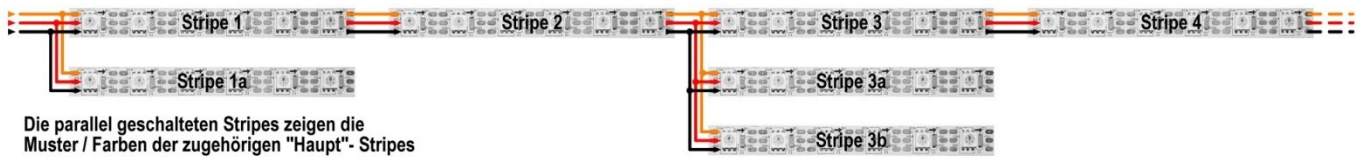
Lightpatterns (Software Version 1.20): *(can vary on future versions)*

The following patterns can be selected thru RC1 at the described threshold levels :

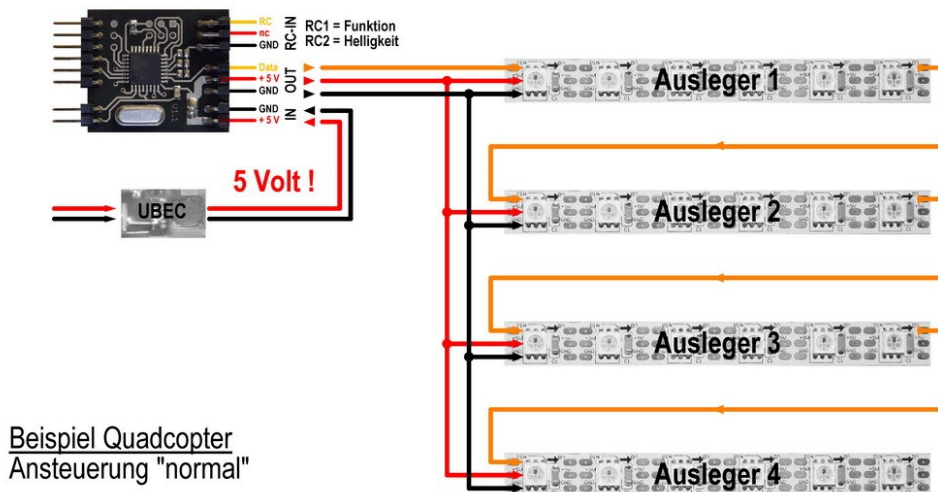
1. (<1200 μ s) OFF
2. (1200 μ s) Landing lights (all LED's white)
3. (1300 μ s) Flightmode 1 (all LED's light in set-up basecolor)
4. (1400 μ s) Flightmode 2 („Kermis“running lights“)
5. (1500 μ s) Flightmode 3 („Double-run“ – fw/rw)
6. (1600 μ s) Flightmode 4 („Triple“, passing thru)
7. (1700 μ s) Flightmode 5 („Fill up and empty“)
8. (1800 μ s) Rainbow glow
9. (1900 μ s) color-circle (segment-by-segment)
10. (2000 μ s) color-circle (passing thru, all segments)

Addendum 1: switching segments in parallel mode to enhance

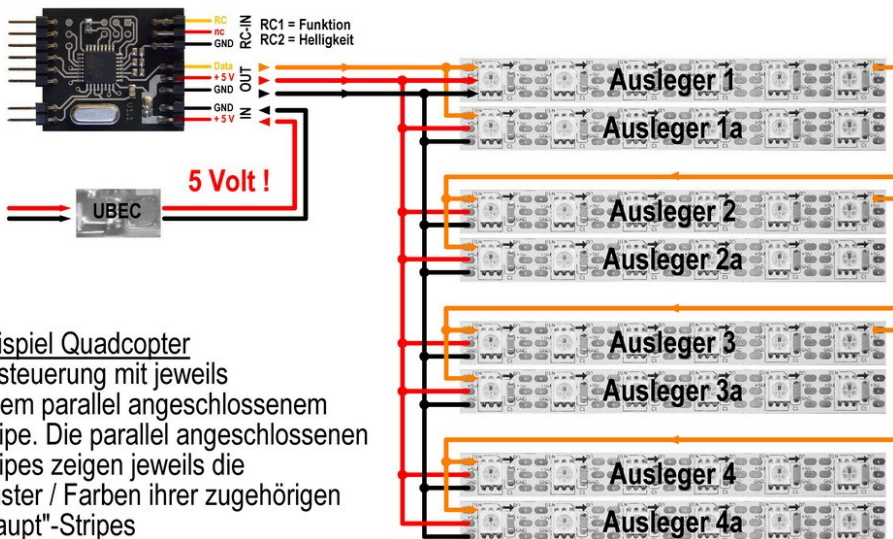
"Parallelschaltung" von Stripes



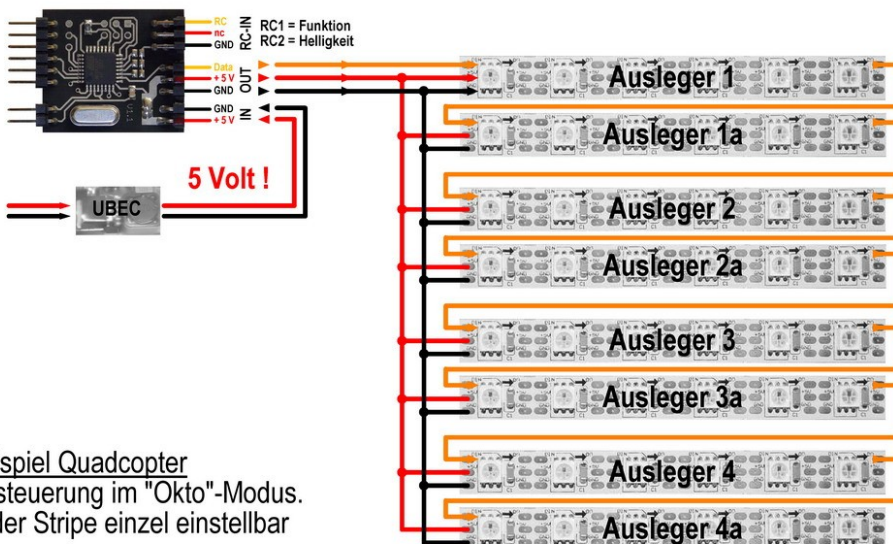
Addendum 2: wiring example - Quadcopter



Beispiel Quadcopter
Ansteuerung "normal"

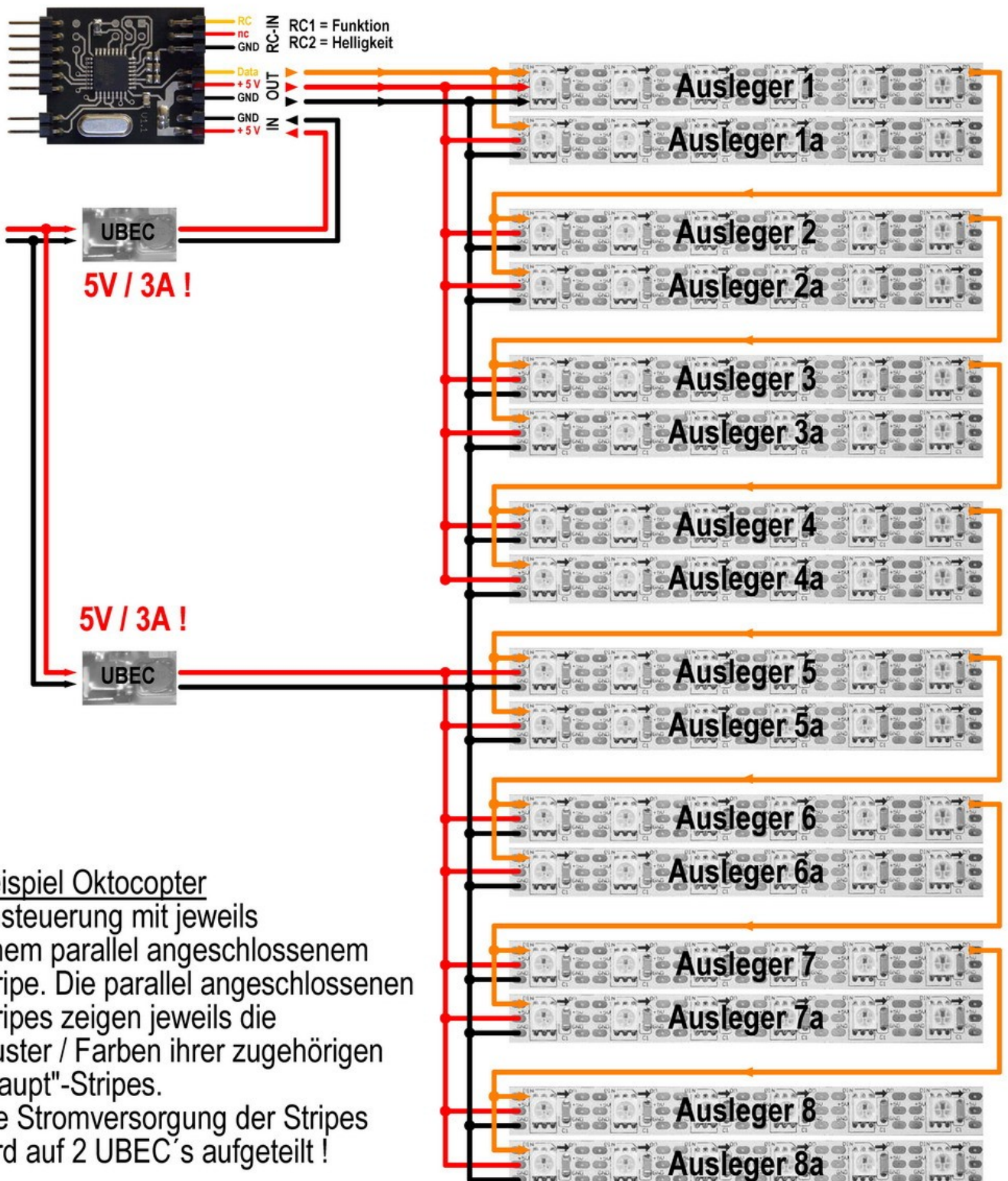


Beispiel Quadcopter
Ansteuerung mit jeweils
einem parallel angeschlossenen
Stripe. Die parallel angeschlossenen
Stripes zeigen jeweils die
Muster / Farben ihrer zugehörigen
"Haupt"-Stripes



Beispiel Quadcopter
Ansteuerung im "Okto"-Modus.
Jeder Stripe einzeln einstellbar

Addendum 3: wiring example - I Oktocopter



Beispiel Oktocopter

Ansteuerung mit jeweils einem parallel angeschlossenen Stripe. Die parallel angeschlossenen Stripes zeigen jeweils die Muster / Farben ihrer zugehörigen "Haupt"-Stripes.

Die Stromversorgung der Stripes wird auf 2 UBEC's aufgeteilt !